

Solving stochastic linear differential equations in MAPLE

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Stochastic differential equations (SDEs) describe physical systems by taking into account some randomness of the system. A general scalar SDE has the form $dX(t) = F(t, X(t)) dt + G(t, X(t)) dW(t)$, where $F : \langle 0, T \rangle \times \mathbb{R} \rightarrow \mathbb{R}$ is the drift coefficient and $G : \langle 0, T \rangle \times \mathbb{R} \rightarrow \mathbb{R}$ is the diffusion coefficient. $W(t)$ is the so called Wiener process, a stochastic process representing the noise. (A stochastic process $W(t)$ is called the Wiener process if it has independent increments, $W(0) = 0$ and $W(t) - W(s)$ distributed $N(0, t - s)$, $0 \leq s < t$). We can represent the SDE in the integral form

$$X(t) = X(t_0) + \int_{t_0}^t F(s, X(s)) ds + \int_{t_0}^t G(s, X(s)) dW(s), \quad (1)$$

where the first integral is an ordinary Riemann integral. Since the sample paths of a Wiener process do not have bounded variation on any time interval, the second integral cannot be a Riemann-Stieltjes integral. K. Itô proposed a way to overcome this difficulty with the definition of a new type of integral, a stochastic integral which is now called the Itô integral (see [4]).

In this paper we consider the scalar linear Itô stochastic differential equation

$$dX(t) = (A_1(t)X(t) + A_2(t)) dt + (B_1(t)X(t) + B_2(t)) dW(t), \quad X(0) = X_0 \quad (2)$$

where the coefficients $A_1(t), A_2(t), B_1(t), B_2(t)$ are functions of time or constants. In the case, when $A_2(t) \equiv 0$ and $B_2(t) \equiv 0$, the equation (2) reduces to the homogeneous bilinear Itô SDE. A general solution of a linear stochastic differential equation, like in the case of a deterministic linear differential equation, can be determined explicitly with the help of an integrating factor or a fundamental solution of an associated homogeneous differential equation.

In the paper we present a MAPLE procedure, called `Linearsde := proc(a, b)`, that solves general linear Itô SDEs of the form (2). The input parameters are $a := A_1x + A_2$ and $b := B_1x + B_2$.

Example 1. We want to solve a linear Itô SDE with constant coefficients and with additive noise ($B_1(t) \equiv 0$):

$$dX(t) = (AX(t) + C) dt + B dW(t), \quad X(0) = 0 \quad (3)$$

> `Linearsde(A*x+C,B);`

$$X[t] = \exp(At) \left(X[0] + \frac{C(\exp(At) - 1) \exp(-At)}{A} + \int_0^t \frac{B}{\exp(As)} dW \right)$$

We put $X(0) = 0$ and then simplify this equation. We get, the solution of the equation (3):

$$X(t) = \frac{C}{A} (e^{at} - 1) + B \int_0^t e^{a(t-s)} dW(s)$$

Now we find the solution of (3) using the Itô calculus. We define a function $g(t, x) = e^{-At}x$, and compute its derivative at point $(t, X(t))$ using the Itô formula (see [4]).

$$\begin{aligned} dg(t, X(t)) &= d(e^{-At}X(t)) = e^{-At}(-A)X(t) dt + e^{-At} dX(t) + 0 (dX(t))^2 = \\ &= -AX(t)e^{-At} dt + e^{-At} ((AX(t) + C) dt + B dW(t)) = Ce^{-At} dt + Be^{-At} dW(t). \end{aligned}$$

This in integral form gives us the solution

$$e^{-At}X(t) - X(0) = C \int_0^t e^{-As} ds + B \int_0^t e^{-As} dW(s),$$

and after some trivial computations we get the same solution as in MAPLE

$$X(t) = \frac{C}{A}(e^{at} - 1) + B \int_0^t e^{a(t-s)} dW(s). \quad (4)$$

Example 2. Let us solve the linear Itô SDE:

$$dX(t) = -X(t) dt + e^{-t} dW(t), \quad X(0) = 0. \quad (5)$$

> Linearsde(-x, exp(-t));

$$X[t] = \exp(-t) \left(X[0] + \int_0^t 1 dW \right)$$

We put $X(0) = 0$ and get the solution of (5) as

$$X(t) = e^{-t} \int_0^t 1 dW = e^{-t} W(t).$$

Now we use the Itô calculus to find the solution of (5). We define the function $g(t, x) = e^t x$, and compute its derivative at point $(t, X(t))$ using the Itô formula.

$$dg(t, X(t)) = d(e^t X(t)) = e^t X(t) dt + e^t dX(t) = e^t X(t) dt + e^t (-X(t)) dt + e^t dW(t) = e^t dW(t).$$

The integral form of this equation is

$$e^t X(t) - X(0) = \int_0^t dW(s) \quad \Rightarrow \quad X(t) = e^{-t} W(t).$$

References

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