

A note to an s-map

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Abstract

The modeling of “quantum probability”, in another words, the study of random events, which are not measurable simultaneously, provides us with interesting results. In this paper we summarising some results from the study of conditionnig non compatible random events.

1 Introduction and basic notion

Conditional probability plays a basic role in the classical probability theory. Some of the most important areas of the theory such as martingales, stochastic processes rely heavily of this concept. Conditional probabilities on a classical measurable space are studied in several different ways, but result in equivalent theories. The classical probability theory does not decscribe the causality model.

The situation charges when non-standard spaces are considered. For example, it is a well known that the set of random events in quantum mechanics experiments is a more general structure than Boolean algebra. In the quantum

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logic approach the set of random events is assumed to be a quantum logic (orthomodular lattice L). Such model we can find not only in the quantum theory, but for example, in the economics, biology etc. We will show such a simple situation in the Example 1.

In this paper we will study a conditional state on a quantum logic using Renyi's approach (or Bayesian principle). This approach helps us to define independence of events and differently from the situation in the classical theory of probability, if an event a is independent of an event b , then the event b can be dependent on the event a (problem of causality) ([13], [?]). We will show that we can define a s -map (function for simultaneous measurements on a quantum logic). It can be shown that if we have the conditional state we can define the s -map and conversely. By using the s -map we can introduce joint distribution also for noncompatible observables on a quantum logic. Moreover, if x is an observable on L and B is Boolean sub-algebra of L , we can construct an observable $z = E(x|B)$, which is a version of conditional expectation of x but it need not to be necessarily compatible with x .

Definition 1.1 *Let L be a nonempty set endowed with a partial ordering \leq . Let there exists the greatest element 1 and the smallest element 0. We consider operations supremum (\vee), infimum \wedge (the lattice operations) and an map $\perp: L \rightarrow L$ defined as follows.*

(i) *For any $\{a_n\}_{n \in \mathcal{A}} \in L$, where $\mathcal{A} \subset \mathcal{N}$ is finite,*

$$\bigvee_{n \in \mathcal{A}} a_n, \bigwedge_{n \in \mathcal{A}} a_n \in L.$$

(ii) *For any $a \in L$ $(a^\perp)^\perp = a$.*

(iii) *If $a \in L$, then $a \vee a^\perp = 1$.*

(iv) *If $a, b \in L$ such that $a \leq b$, then $b^\perp \leq a^\perp$.*

(v) If $a, b \in L$ such that $a \leq b$ then $b = a \vee (a^\perp \wedge b)$ (orthomodular law).

Then $(L, 0, 1, \vee, \wedge, \perp)$ is said to be the orthomodular lattice (briefly OML).

Let L be an OML. Then elements $a, b \in L$ will be called:

- *orthogonal* ($a \perp b$) iff $a \leq b^\perp$;
- *compatible* ($a \leftrightarrow b$) iff there exist mutually orthogonal elements $a_1, b_1, c \in L$ such that

$$a = a_1 \vee c \quad \text{and} \quad b = b_1 \vee c.$$

Definition 1. 2 A map $m : L \rightarrow [0, 1]$ such that

- (i) $m(0) = 0$ and $m(1) = 1$.
- (ii) If $a \perp b$ then $m(a \vee b) = m(a) + m(b)$

is called a state on L .

Definition 1. 3 [13] Let L be an OML. A subset $L_0 \subset L - \{0\}$ is called a conditional system (CS) in L if the following conditions hold:

- If $a, b \in L_0$, then $a \vee b \in L_0$.
- If $a, b \in L_0$ and $a < b$, then $a^\perp \wedge b \in L_0$.

Let $A \subset L$. Then $L_0(A)$ is the smallest CS, that contains the set A .

Definition 1. 4 [13] Let L be an OML and let L_0 be a CS in L . Let $f : L \times L_0 \rightarrow [0, 1]$. If the function f fulfills the following conditions:

- (C1) for each $a \in L_0$ $f(., a)$ is a state on L ;
- (C2) for each $a \in L_0$ $f(a, a) = 1$;

(C3) if $\{a_i\}_{i=1}^n \in L_0$ and a_i are mutually orthogonal, then for each $b \in L$

$$f(b, \bigvee_{i=1}^n a_i) = \sum_{i=1}^n f(a_i, \bigvee_{i=1}^n a_i) f(b, a_i);$$

then it is called a conditional state.

Definition 1. 5 [13] Let L be an OML and f be a conditional state. Let $b \in L$, $a, c \in L_0$ such that $f(c, a) = 1$. Then b is independent of a with respect to the state $f(., c)$ ($b \asymp_{f(., c)} a$) if $f(b, c) = f(b, a)$.

If L_0 be CS and $f : L \times L_0 \rightarrow [0, 1]$ is a conditional state, then ([13])

- (i) Let $a^\perp, a, c \in L_0$, $b \in L$ and $f(c, a) = f(c, a^\perp) = 1$. Then $b \asymp_{f(., c)} a$ if and only if $b \asymp_{f(., c)} a^\perp$.
- (ii) Let $a, c \in L_0$, $b \in L$ and $f(c, a) = 1$. Then $b \asymp_{f(., c)} a$ if and only if $b^\perp \asymp_{f(., c)} a$.
- (iii) Let $a, c, b \in L_0$, $b \leftrightarrow a$ and $f(c, a) = f(c, b) = 1$. Then $b \asymp_{f(., c)} a$ if and only if $a \asymp_{f(., c)} b$.

2 An s-map

Definition 1. 6 Let L be an OML. The map $p : L^n \rightarrow [0, 1]$ will be called s-map if the following conditions are met:

- (s1) $p(1, \dots, 1) = 1$;
- (s2) if there exist i, j , such that $a_i \perp a_j$, then $p(a_1, \dots, a_n) = 0$;
- (s3) if $a_i \perp b_i$, then

$$p(a_1, \dots, a_i \vee b_i, \dots, a_n) = p(a_1, \dots, a_i, \dots, a_n) + p(a_1, \dots, b_i, \dots, a_n),$$

for $i = 1, \dots, n$.

Definition 3. 1 Let x be an observable on L and B be a Boolean sub-algebra of L and f be conditional state on L such that $L_c = L - \{0\}$. Then the observable z will be called a conditional expectation of x with respect to B in the state $f(., 1)$ iff for any $b \in B - \{0\}$

$$f(x, b) = f(z, b).$$

We will denote $z := E_f(x|B)$.

It is clear that if L be a Boolean algebra, then $E_f(x|B)$ is known the conditional expectation.

Proposition 2. 1 Let L be an OML and let p be an s -map. Then

- (1) if $a_i \perp a_j$, then $p(a_1, \dots, a_n) = 0$;
- (2) for any $a \in L$, a map $\nu : L \rightarrow [0, 1]$, such that $\nu(a) := p(a, \dots, a)$ is a state on L ;
- (3) for any $(a_1, \dots, a_n) \in L^n$ $p(a_1, \dots, a_n) \leq \nu(a_i)$ for each $i = 1, \dots, n$;
- (4) if $a_i \leftrightarrow a_j$, then

$$p(a_1, \dots, a_n) = p(a_1, \dots, a_{i-1}, a_i \wedge a_j, \dots, a_j \wedge a_i, a_{j+1}, \dots, a_n).$$

Let $\bar{a} = (a_1, \dots, a_n) \in L^n$. Let us denote $\pi(\bar{a})$ a permutation of (a_1, \dots, a_n) .

Proposition 2. 2 Let L be an OML. Let p be an s -map and let $(a_1, \dots, a_n) \in L^n$.

- (1) If there exists $i \in \{1, \dots, n\}$, such that $a_i = 1$, then

$$p(a_1, \dots, a_n) = p(a_1, \dots, a_{i-1} \cdot a_j, a_{i+1}, \dots, a_n)$$

for each $j = 1, \dots, n$.

(2) If there exist $i \neq j$ such that $a_i = a_j$, then

$$p(a_1, \dots, a_n) = p(\pi(a_1, \dots, a_n)).$$

(3) If there exist i, j such that $a_i \leftrightarrow a_j$, then

$$p(a_1, \dots, a_n) = p(\pi(a_1, \dots, a_n)).$$

Let $\Pi(\bar{a})$ be the set of all permutations and let

$$\bar{a}_{(k)}^{(i)} = (a_1, \dots, a_{k-1}, a_k, a_{k+1}, \dots, a_{i-1}, a_k, a_{i+1}, \dots, a_n).$$

Corollary 2. 1 Let L be an OML. Let p be an s -map and let $\bar{a} \in L^n$.

(1) If there exists $i \in \{1, \dots, n\}$, such that $a_i = 1$, then

$$p(\bar{a}) = p(\bar{b})$$

for each $\bar{b} \in \bigcup_k \Pi(\bar{a}_{(k)}^{(i)})$.

(2) If there exist $i \neq j$ such that $a_i = a_j$, then

$$p(\bar{a}) = p(\bar{b})$$

for each $\bar{b} \in \bigcup_k \Pi(\bar{a}_{(k)}^{(i)})$.

(3) If there exist i, j such that $a_i \leftrightarrow a_j$, then

$$p(\bar{a}) = p(\bar{b})$$

for each $\bar{b} \in \bigcup_k \Pi(\bar{a}_{(k)}^{(i)})$.

Example 2. 1 Let $n = 3$ and $a, b \in L$. If $\bar{a} = (a, a, b)$, then $\Pi(\bar{a}) = \{(a, a, b), (b, a, a), (a, b, a)\}$ and $\bar{a}_{(3)}^{(1)} = (b, a, b)$, $\bar{a}_{(3)}^{(2)} = (a, b, b)$, $\bar{a}_{(2)}^{(1)} = (a, a, b)$. Hence

$$p(a, a, b) = p(a, b, a) = p(b, a, a) = p(b, b, a) = p(a, b, b) = p(b, a, b).$$

Let $n = 4$ and $a, b, c \in L$. If $\bar{a} = (a, b, c, c)$, then $\bar{a}_{(2)}^{(4)} = (a, b, c, b)$ and

$$p(a, a, b, c) = p(a, b, c, a) = p(b, b, c, a) = \dots = p(c, a, b, c).$$

Definition 3. 2 Let L be an OML and let p be an s -map. If x_1, \dots, x_n are observables on L , then the map

$$p_{x_1, \dots, x_n} : \mathcal{B}(R)^n \rightarrow [0, 1],$$

such that

$$p_{x_1, \dots, x_n}(E_1, \dots, E_n) = p(x_1(E_1), \dots, x_n(E_n))$$

is called the joint distribution of the observables x_1, \dots, x_n .

Definition 3. 3 Let L be an OML and let p be an s -map. If x_1, \dots, x_n be observables on L , then the map

$$F_{x_1, \dots, x_n} : R^n \rightarrow [0, 1],$$

such that

$$F_{x_1, \dots, x_n}(r_1, \dots, r_n) = p(x_1(-\infty, r_1), \dots, x_n(-\infty, r_n))$$

is called the joint distribution function of the observables x_1, \dots, x_n .

Definition 3. 4 Let L be an OML and let p be an s -map. If x_1, \dots, x_n be observables on L , then a marginal distribution function is

$$\lim_{x_i \rightarrow \infty} F_{x_1, \dots, x_i, \dots, x_n}(r_1, \dots, r_i, \dots, r_n).$$

Definition 3. 5 Let L be an OML and let p be an s -map. Let x_1, \dots, x_n be observables on L and F_{x_1, \dots, x_n} be the joint distribution function of the observables x_1, \dots, x_n . Then we say, that F_{x_1, \dots, x_n} has the property of commutativity if for each $(r_1, \dots, r_n) \in R^n$

$$F_{x_1, \dots, x_n}(r_1, \dots, r_n) = F_{\pi(x_1, \dots, x_n)}(\pi(r_1, \dots, r_n)).$$

It is clear that F_{x_1, \dots, x_n} has the property of commutativity if and only if

$$p(x_1(E_1), \dots, x_n(E_n)) = p(\pi(x_1(E_1), \dots, x_n(E_n))),$$

for each $E_i \in \mathcal{B}(R)$, $i = 1, \dots, n$.

Proposition 3. 1 *Let L be an OML and let p be an s -map. Let $x_1, \dots, x_n \in \mathcal{O}$ and let $F_{x_1, \dots, x_n}(r_1, \dots, r_n)$ be the joint distribution function of the observables x_1, \dots, x_n .*

(1) *For each $(r_1, \dots, r_n) \in R^n$ $0 \leq F_{x_1, \dots, x_n}(r_1, \dots, r_n) \leq 1$;*

(2) *If $r_i \leq s_i$, then $F_{x_1, \dots, x_n}(r_1, \dots, r_i, \dots, r_n) \leq F_{x_1, \dots, x_n}(r_1, \dots, s_i, \dots, r_n)$.*

(3) *For each $i = 1, \dots, n$*

$$\lim_{r_i \rightarrow \infty} F_{x_1, \dots, x_n}(r_1, \dots, r_n) = F_{x_1, \dots, x_n}(r_1, \dots, r_{i-1}, 1, r_{i+1}, \dots, r_n).$$

(4) *For each $i = 1, \dots, n$*

$$\lim_{r_i \rightarrow -\infty} F_{x_1, \dots, x_n}(r_1, \dots, r_n) = 0.$$

(5) *If there exist i, j , such that $i \neq j$ and $x_i \leftrightarrow x_j$, then*

$$F_{x_1, \dots, x_n}(r_1, \dots, r_n) = F_{\pi(x_1, \dots, x_n)}(\pi(r_1, \dots, r_n)).$$

Proposition 3. 2 *Let L be an OML and let p be an s -map. Let $x_1, \dots, x_n \in \mathcal{O}$ and let $F_{x_1, \dots, x_n}(r_1, \dots, r_n)$ be the joint distribution function. Compatibility of just two observables imply the total commutativity.*

Proposition 3. 3 *Let L be an OML and let $x_1, \dots, x_n \in \mathcal{O}$. Then there exist a probability space $(\Omega, \mathfrak{F}, P)$ and random variables ξ_1, \dots, ξ_n on it, such that*

$$F_{x_1, \dots, x_n}(r_1, \dots, r_n) = F_{\xi_1, \dots, \xi_n}(r_1, \dots, r_n)$$

and P_{ξ_i} such that

$$P_{\xi_i}((-\infty, r)) = \nu(x_i(-\infty, r)),$$

where $r \in R$ and $i = 1, \dots, n$ is the probability distribution of the random variable ξ_i ,

If we consider a quantum model as an OML, a marginal distribution function defined by using an s -map has the property of commutativity. It follows that, in general, it need not be true that

$$F_{x_1, \dots, x_n}(t_1, \dots, t_n) = F_{x_1, \dots, x_{n+1}}(t_1, \dots, t_n, \infty),$$

where $F_{x_1, \dots, x_n}(t_1, \dots, t_n)$, $F_{x_1, \dots, x_{n+1}}(t_1, \dots, t_n, \infty)$ are joint distribution functions and x_1, \dots, x_{n+1} are observables on L . Consequently, we can find such an s -map and an s_{n+1} -map such that

$$p(a_1, \dots, a_n) \neq p(a_1, \dots, a_n, 1)$$

on L . Moreover if

$$p(a_1, \dots, a_n) = p(a_1, \dots, a_n, 1)$$

on L , then the s -map has the property of commutativity. This is not true in general, either ([16]).

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